

TORQUEMASTER

BRUSH SERVO MOTORS

3500 SERIES

MTI-Torque Systems specializes in the design of high performance brush servo motors that provide efficiency, flexibility of application, and a long and trouble-free service life. Our TORQUEMASTER® 3500 series is no exception, when integrated with high performance brush amplifiers, TORQUE-MASTER 3500 Series brush servo motors provide effective and highly efficient motion control solutions for a wide range of applications including factory automation, packaging, robotics, machine tools, medical instrumentation and more.



Performance Benefits:

- Delivers smooth and superior low speed performance, and maximum power ratings with low thermal resistance for high speed performance.
- Maximum torque in a smaller package
- Rugged industrial construction
- Continuous torque ratings up to 10.6 in-lbs with speeds up to 4600 RPM (*no load*)
- Peak torque ratings up to 94 in-lbs
- IP65 Sealing available
- High torque-to-inertia ratio delivers maximum torque per frame size
- Numerous custom options available

Design Features:

- Latest in high performance permanent magnet technology, and are available in eight standard windings as well as custom windings
- Motors can be customized to fit your exact application with tachometers, encoders, brakes and other options.
- Specialized machinery designs can install or retrofit servomotor with little or no restrictions
- Multiple configurations accommodate flexible design considerations
- Performance enhancement and feature convenience that allows Torque Systems motors to be incorporated into a broader range of applications



BRUSH SERVO MOTOR CHARACTERISTICS

	SYMBOL	UNITS	3505	3509	3515	3528	
	T _C	Cont. Torque	Lb-In	2.63	4.25	6.44	10.63
	T _P	Peak Torque	Lb-In	21.9	37.5	56.3	93.8
	T _F	Static Friction	Lb-In	0.3	0.25	0.3	0.32
	F _i	Viscous Friction	Lb-In/KRPM	0.07	0.08	0.09	0.14
	T _R	Cogging Torque	Lb-In	0.09	0.06	0.07	0.11
	J _M	Inertia	Lb-In-sec ²	0.004	.0006	.0008	.0015
	R _{TH}	Thermal Res	Deg C/watt	4.2	3.7	3.1	2.3
	T _{TH}	Thermal Time	Minute	15	15	20	25
	t _m	Mech Time	Millisec	8.1	5.5	3.9	3.5
	t _e	Elect Time	Millisec	1.5	1.5	1.7	2
	F _C	Commutation	Watts x Lb In / Amps	1475	2060	2990	4960
	Wt	Weight	Lbs	3.2	3.8	5	7.5

Note: All values at 25°C Ambient.

WINDING

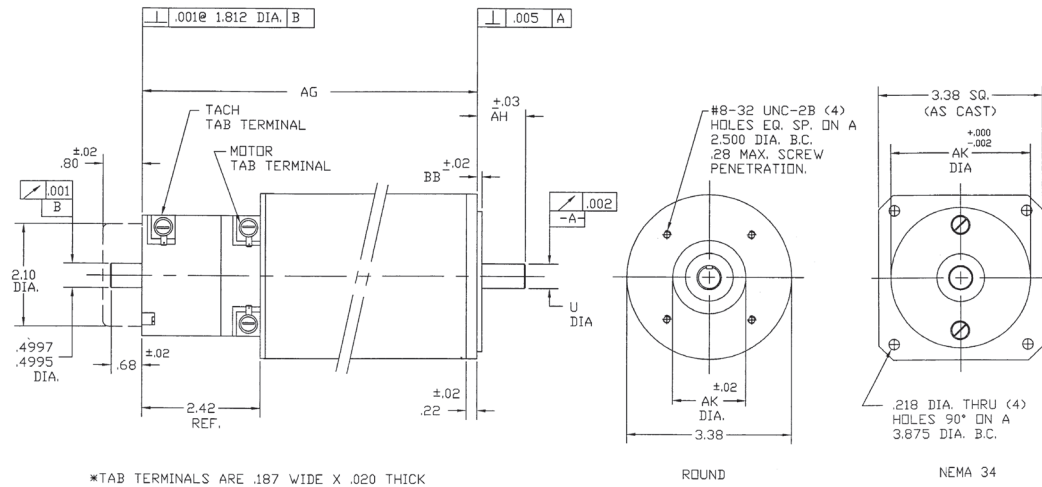
A	K _T	Torq. Sens.	Lb-In/Amp	0.24	0.39	0.59	1.05
	R _A	Arm. Resis.	Ohms	0.13	0.16	0.2	0.3
	K _V	Back E.M.F	Volts/KRPM	2.8	4.6	7.0	12.4
	F _C /K _T	P _b	Watts	388	332	315	295
B	K _T	Torq. Sens.	Lb-In/Amp	0.31	0.52	0.79	1.4
	R _A	Arm. Resis.	Ohms	0.22	0.27	0.34	0.51
	K _V	Back E.M.F	Volts/KRPM	3.7	6.1	9.4	16.6
	F _C /K _T	P _b	Watts	295	248	235	221
C	K _T	Torq. Sens.	Lb-In/Amp	0.39	0.65	0.99	1.74
	R _A	Arm. Resis.	Ohms	0.44	0.53	0.67	1.01
	K _V	Back E.M.F	Volts/KRPM	4.7	7.7	11.8	20.6
	F _C /K _T	P _b	Watts	234	198	188	178
D	K _T	Torq. Sens.	Lb-In/Amp	.5	.82	1.26	2.21
	R _A	Arm. Resis.	Ohms	0.55	0.67	0.84	1.3
	K _V	Back E.M.F	Volts/KRPM	5.9	9.7	14.9	26.2
	F _C /K _T	P _b	Watts	184	157	148	140
E	K _T	Torq. Sens.	Lb-In/Amp	.63	1.04	1.59	2.79
	R _A	Arm. Resis.	Ohms	0.88	1.05	1.34	2.04
	K _V	Back E.M.F	Volts/KRPM	7.5	12.3	18.8	33.0
	F _C /K _T	P _b	Watts	146	124	117	111
F	K _T	Torq. Sens.	Lb-In/Amp	.79	1.29	1.99	3.5
	R _A	Arm. Resis.	Ohms	1.4	1.7	2.12	3.2
	K _V	Back E.M.F	Volts/KRPM	9.3	15.3	23.5	41.3
	F _C /K _T	P _b	Watts	117	100	94	89
G	K _T	Torq. Sens.	Lb-In/Amp	1.0	1.64	2.52	4.43
	R _A	Arm. Resis.	Ohms	2.2	2.7	3.4	5.12
	K _V	Back E.M.F	Volts/KRPM	11.8	19.4	29.8	52.3
	F _C /K _T	P _b	Watts	92	78	74	70
H	K _T	Torq. Sens.	Lb-In/Amp	1.26	2.08	3.18	5.59
	R _A	Arm. Resis.	Ohms	3.52	4.3	5.4	8.14
	K _V	Back E.M.F	Volts/KRPM	14.9	24.5	37.6	66.1
	F _C /K _T	P _b	Watts	73	62	59	55

Note: Continuous torque specifications obtained with motor mounted to an 10" x 10" x 0.25" alum. plate at 25 C° ambient. Typical values are within ±10% of rating.

For custom designs please consult factory.

All specifications subject to change without notice.

MECHANICAL SPECIFICATIONS*



DIMENSION CHART*

MOTOR	AG	AG	U DIA.		AH		AK	AF	BB	
	Motor Only Inches (Metric)	Motor Tach Inches (Metric)	STD	NEMA	STD	NEMA	STD	NEMA	STD	NEMA
3505	2.49 (63.2)	4.00 (101.6)	.5000/.4995	.3750/.3745	1.00	1.19	1.500	2.875	0.10	0.06
3509	3.24 (82.3)	4.75 (120.7)	.5000/.4995	.3750/.3745	1.00	1.19	1.500	2.875	0.10	0.06
3515	3.99 (101.3)	5.50 (139.7)	.5000/.4995	.3750/.3745	1.00	1.19	1.500	2.875	0.10	0.06
3528	5.24 (133.1)	6.75 (171.5)	.5000/.4995	.3750/.3745	1.00	1.19	1.500	2.875	0.10	0.06

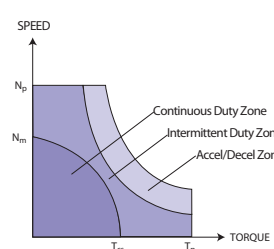
Note: Consult factory for AG length with cover option.

METRIC (mm): DIMENSIONS ALL FRAME SIZES

SHAFT: DIA	12h6	MOUNTING: PILOT	38
LENGTH	25.0	B.C.	63.5
		HOLE SIZE	6.6

*All specifications are for reference only. Please consult the factory for certified dimension drawings. Standard Direction of Rotation: CCW rotation viewed from shaft end with red motor terminal positive with respect to black motor terminal.

TORQUE PERFORMANCE CURVES



NOTE: Continuous torque specifications obtained with motor mounted to an 10"x10"x.25" aluminum plate at 25 C° ambient. Typical values are within ±10% of rating.

STANDARD WINDING SPEED/TORQUE CURVE DATA FOR SIZING A SERVO MOTOR

Nm = Maximum speed, continuous operation

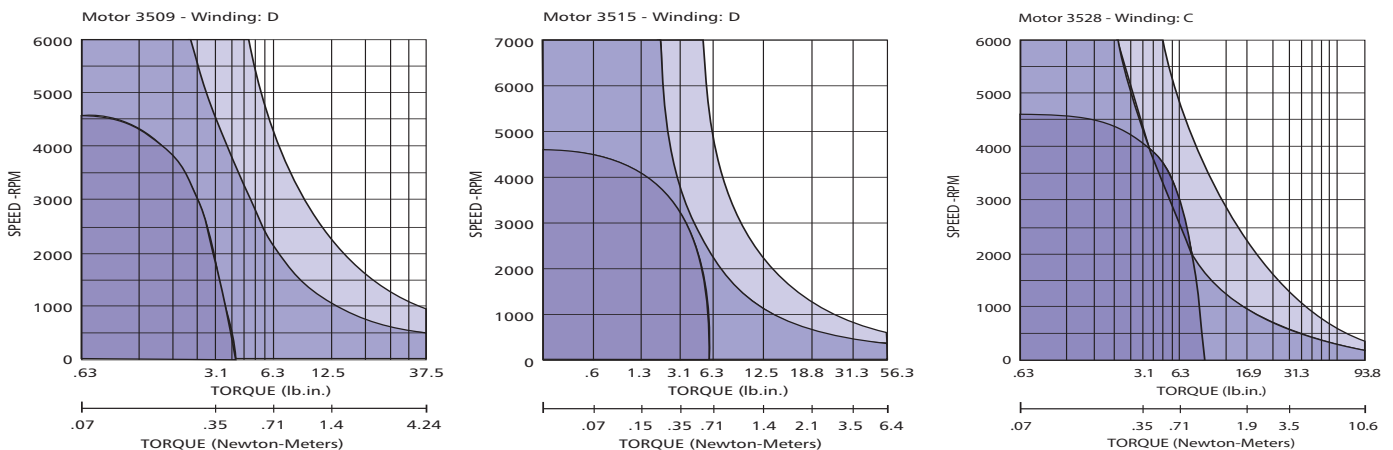
Np = Peak speed, acceleration/deceleration and intermittent duty

Tcs = Continuous stall torque

Tp = Peak torque

All specifications subject to change without notice.

TORQUE PERFORMANCE CURVES



Torque Speed Curves of other windings available, consult factory.

VOLTAGE EQUATION FOR MOTORS

Volts = $\frac{K_T \times \text{RPM}}{1,350} + \frac{T \times R_A}{K_T} + V_B$

Where:

K_T = torque constant, oz.-in. per amp
 T = load torque plus motor friction torque-oz.-in.
 R_A = armature resistance + brush resistance
 V_B = brush voltage drop = 2 volts

Note: For armature resistance at maximum temperature rating, multiply catalog value of R by 1.5

MOTOR TORQUE RATING VS. SPEED

$T_R = .94K_T \left[\frac{130}{R_{TH}} - \frac{\text{RPM} \times T_F}{1,350} - \frac{\text{RPM}^2 \times F_i}{1,350,000} \right]^{1/2} - T_F - \left[\frac{\text{RPM} \times F_i}{1000} \right]$

Where:

T_R = rated torque (25°C ambient)-oz.-in.
 K_T = torque sensitivity-oz.-in./amp
 R_A = armature resistance
RPM = revolutions per minute
 T_F = static friction torque-oz.-in.
 F_i = viscous friction-oz.-in.
 R_{TH} = thermal resistance

To Find: Higher Torque Rating for Intermittent Duty

Let A = $\frac{\text{total cycle time in seconds}}{\text{thermal time constant of motors in seconds}}$

Let B = $\frac{\text{"on" time in seconds per cycle}}{\text{thermal time constant of motor in seconds}}$

then with T_R = Rated torque for 100% duty
and T_{MAX} = Rated torque for intermittent duty

$T_{MAX} = T_R \times \left[\frac{1 - e^{-A}}{1 - e^{-B}} \right]^{1/2}$

ORDERING INFORMATION (For Standard Options)

35

XX

X

XX

XX

SERIES

LAM STACK

TACH

COMMUTATION/MAGNET

ENCODER

05

09

15

28

0 = None

T = Tach

00 = STD

00 = None

M0 = Mod. Enc Prep

QC = 500

QE = 1024

QD = 1000

QG = 2000

QH = 2048

QJ = 2500

QK = 5000

SX = Special

XX

X

X

X

X

MTG PLATE

A = 3 3/8" Round

C = 3 3/8" Square (NEMA 34)

M = Metric (85.6mm Square)

S = Special

SHAFT

A = 1/2" dia. x 1" lg.

B = A plus 1/8" x .75" lg. keyway

E = 3/8" dia. x 1.19" lg. (NEMA 34)

M = Metric, 12mm dia x 33mm lg. keyway

S = Special

TERMINATION (see note below)

T = Tab terminals (std)

S = Screw terminals (optional)

W = 3 foot leads attached to tab terminals (optional)

Y = Cover w/3 foot long leads and cord grip (optional)

C = Cover w/MS 3102A-20-27P

M = Cover w/NPT

SEALING

0 = No sealing

B = IP65 w/o shaft seal

S = IP65

Requires "Y, C, or M" Cover Option from TERMINATION list above

BRAKE

00 = No Brake

B1 = 15 lb-in, 24 VDC

X

WINDINGS

MOTOR

A THRU H

X

WINDINGS

TACH

(V/KRPM)

0 = None

E = 3

F = 7

G = 15

NOTE:

Cover Option – consult factory for overall motor length.

CUSTOMIZE THE 3500 SERIES TO YOUR EXACT REQUIREMENTS

To satisfy various applications with cost-effective solutions, 3500 Series motors are readily available with a wide range of standard capabilities. Final designs are often the result of cooperative efforts between the customer's engineering department and MTI-Torque Systems. For assistance, call your local distributor or Torque Systems direct. We look forward to meeting your custom requirements.

ASK ABOUT OTHER MOTION CONTROL SOLUTIONS & CAPABILITIES FROM TORQUE SYSTEMS

- Brushless TorqueMaster® Servo Motor
- Gearboxes/Brakes
- Expert application engineering
- Complete repair & refurbishing services